

An Aspect-Oriented Paradigm for Component-based Systems and its Application to RV

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COST Meeting



Outline

- 1 Introduction
- 2 Preliminaries
- 3 Crosscutting Concerns in BIP
- 4 The AOP-BIP Tool and the Network example
- 5 Applications to RV
- 6 Conclusion

Component-Based Design

- Separation between **computation** and **coordination**:
 - ① Design of individual components: components are **white-boxes**;
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 - ① Design of individual components: components are **white-boxes**;
 - ② Coordination between various components: components are **black-boxes**.
- Advantages:
 - ① Re-usability of components
 - ② Ability to make internal changes to components without affecting system
 - ③ Compositional construction, testing and verification

Aspect-Oriented Programming

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“domain used as a decomposition criterion for a system or another domain with that concern”

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- Concerns that are spread out or overlap are called **crosscutting**.

Crosscutting Concerns

- Crosscutting concerns lead to two typical problems:
 - 1 **Tangling**: occurs when concerns **overlap** in one region of the system.
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- Aspect-Oriented Programming seeks to **modularize crosscutting concerns**.

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Aspect

The module that wraps a set of pointcuts, their associated advices and extra **context information**.

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- Motivation
 - ① **Reliability**: correct-by-construction, verification, validation
 - ② **Maintenance**: encapsulation of concerns
 - ③ **Refinement**: progressive building of complex systems

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Advantages

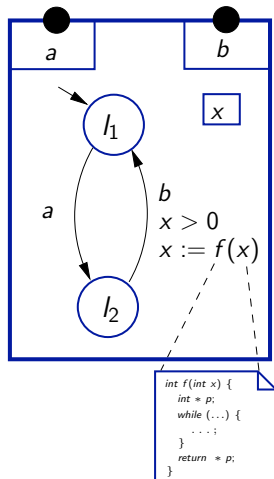
- 1 **Specification** of both atomic components and their coordination using well-defined **operational semantics**;
- 2 Efficient **code generation**.
- 3 Automatic **verification** and **validation**.

Behavior

Atomic Component

Labelled Transition System with data:

- *ports*, e.g. $\{a, b\}$
- *control locations*, e.g. $\{l_1, l_2\}$
- *variables*, e.g. $\{x\}$
- *transitions*
 - guards, e.g., $x > 0$
 - variable modifications (with external functions), e.g., $x := f(x)$



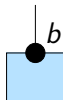
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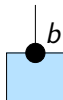


Interaction (= “a communication/collaboration”)

An **interaction** is defined as a set of ports

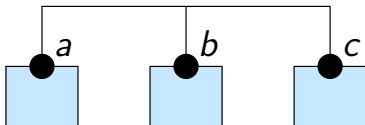
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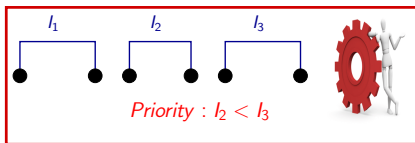
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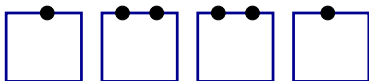
Composite component

available atomic components + interactions + priority rules



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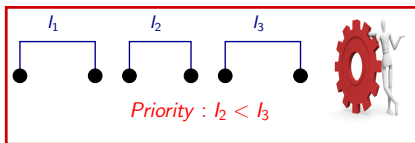
Engine Protocol



Composite component

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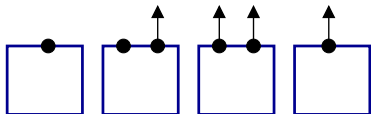
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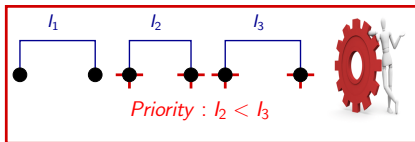
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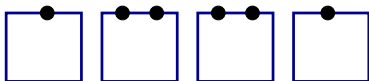
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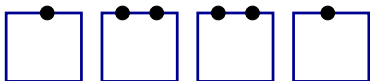
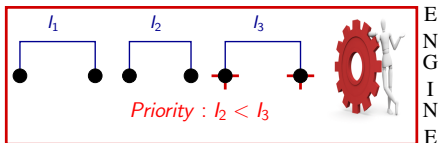
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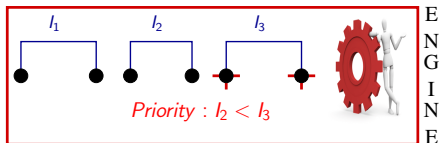
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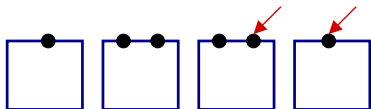
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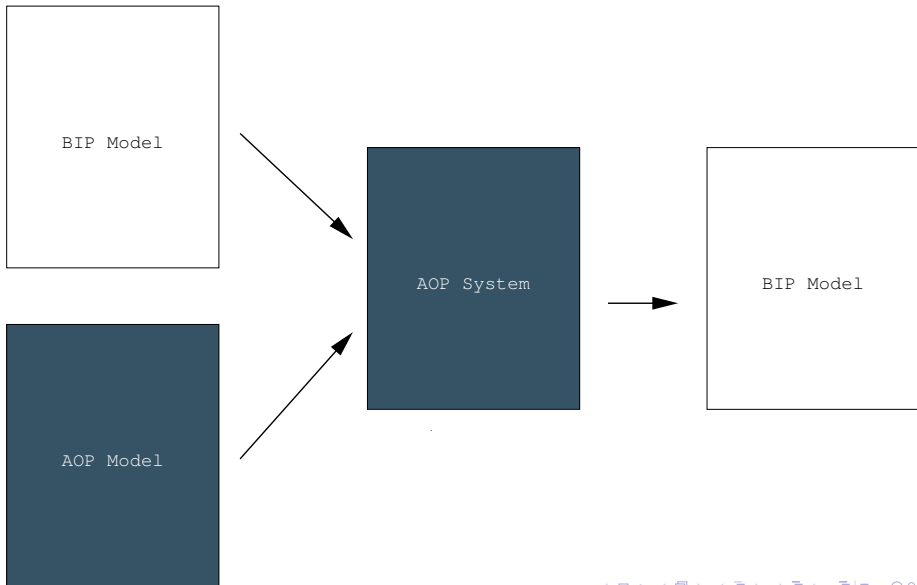
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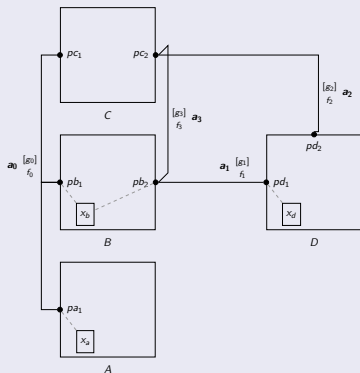


High-Level View

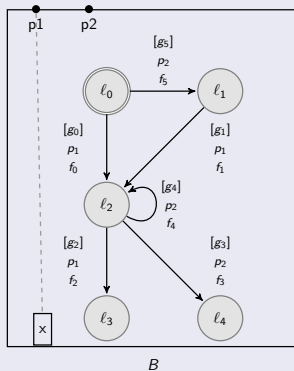


System Views

Global View



Local View



Execution Trace

Trace

- Alternating sequence of **global state** and **interaction execution**
($q_0, a_0, q_1, \dots, q_{i-1}, a_{i-1}, q_i$)
- Global State: states of all atomic components
 - Location
 - Variable valuations

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Global Event

- Starting global state \rightarrow Interaction execution \rightarrow Next global state
- $\langle q_k, a_k, q_{k+1} \rangle$ for $k \in [0, i - 1]$
- $a_k = \langle p_k, f_k, g_k \rangle$

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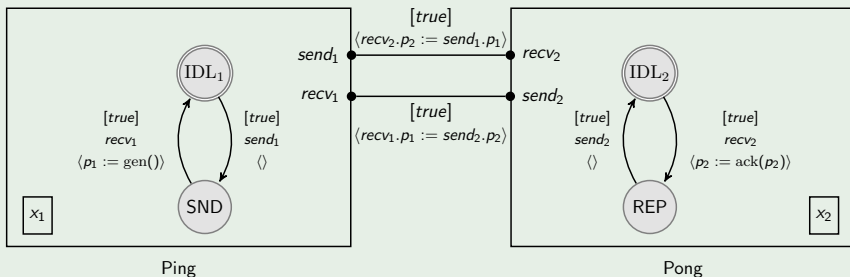
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Global Joinpoint

A global joinpoint is a global event.

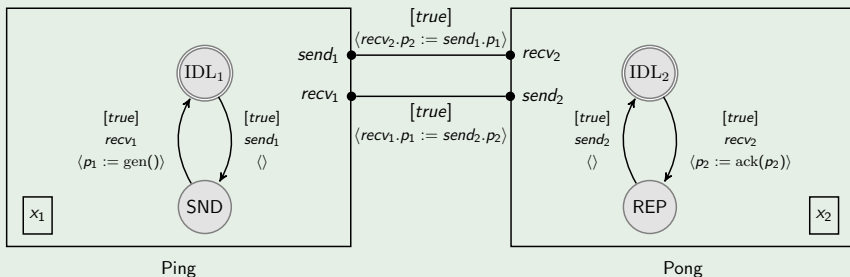
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Example (Global Event)



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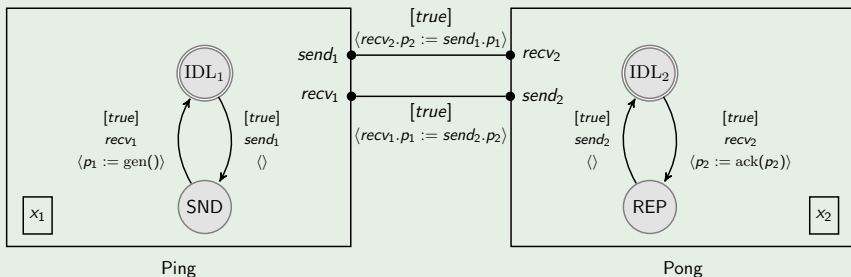
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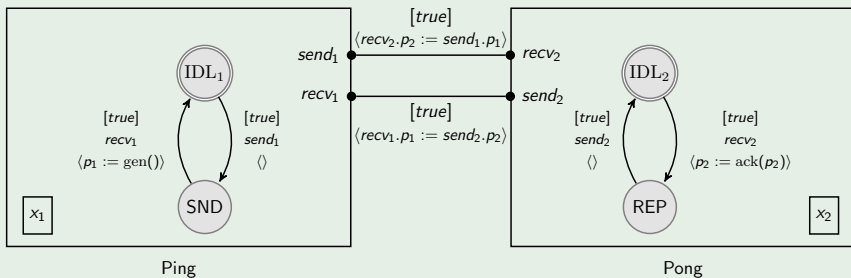
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- It can express the following:
 - ① **Synchronization** between various atomic components;
 - ② **Data transfer** between various atomic components.
 - ① One ore more components are **sending** data.
 - ② One or more components are **receiving** data.

Global Pointcut

Global Pointcut Expression

A global pointcut expression is defined as $gpc = \langle p, v_r, v_w \rangle$:

- 1 p : matches a subset of **ports** associated with the matching interaction.
- 2 v_r : variables **read**.
- 3 v_w : variables **modified** .

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Matching Global Joinpoints

$\langle q, a, q' \rangle \models \langle p, v_r, v_w \rangle$ iff $p \subseteq a.ports$

$\wedge v_r \subseteq readvar(a.func)$

$\wedge v_w \subseteq writevar(a.func)$

Global Advice

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- The functions f_b , f_a are only defined over:
 - ① Extra inter-type variables V .
 - ② The variables of the **context**: the variables of the ports in the pointcut expression.

Global Weaving: Matching

- We use interactions as the base unit of instrumentation

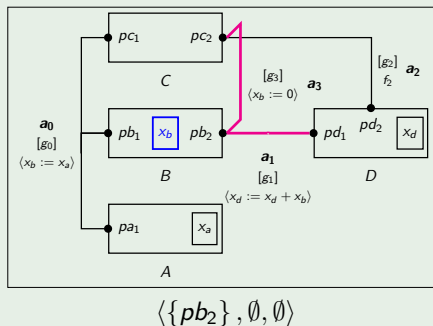
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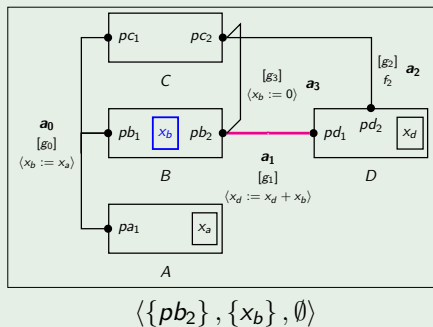
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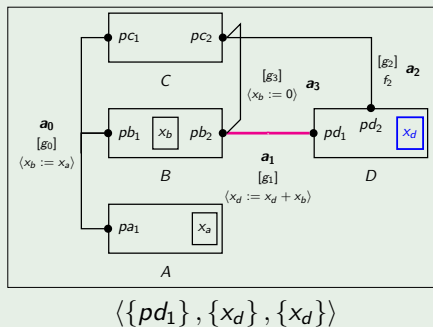
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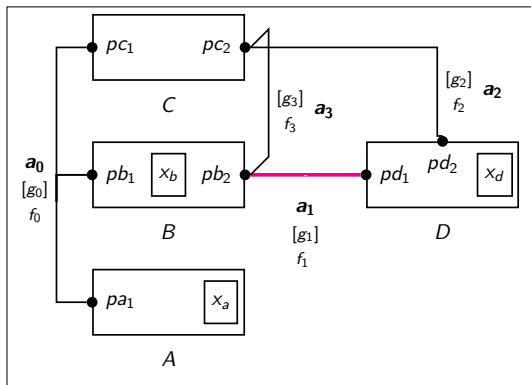
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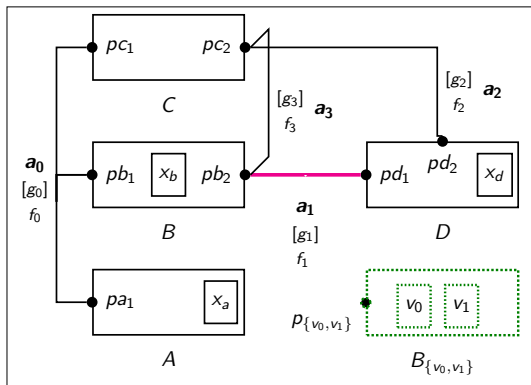
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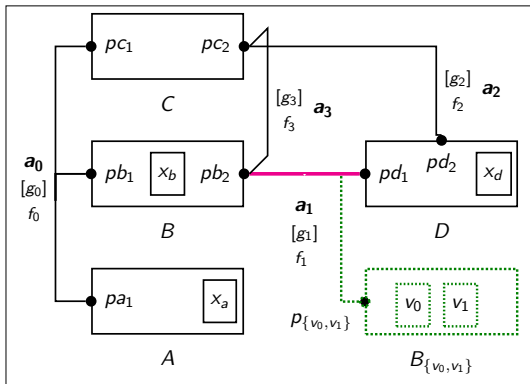
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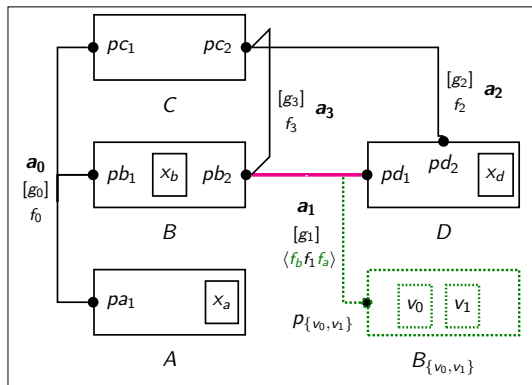
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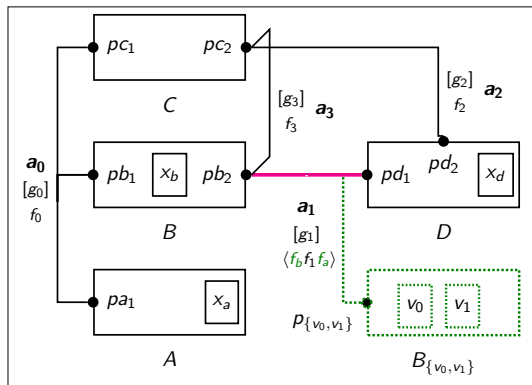
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- 5 Priority is **unchanged**



Global Aspect and Correctness

Global Aspect

- A global aspect is defined on a **composite component** it contains:
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Proposition: Correctness of a Single Weave

- Consider all events in the **resulting** system
- Define rem_g that **removes** the advice from the global event (if it exists)
- Verify that the advice is applied to an event e iff $\text{rem}_g(e) \models gpc$

Local Execution Trace

Projection

Extract the local state from the global state: $q = \langle q_0, \dots, q_n \rangle, q \upharpoonright B_k = q_k$

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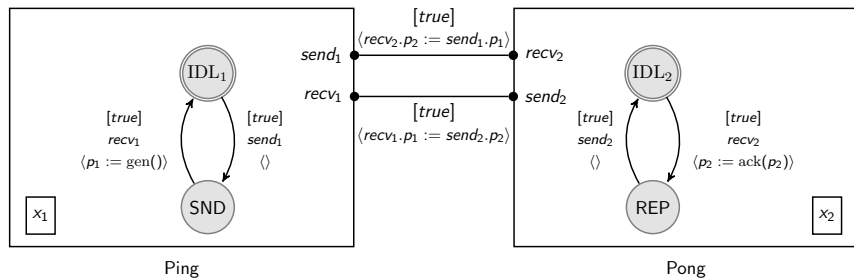
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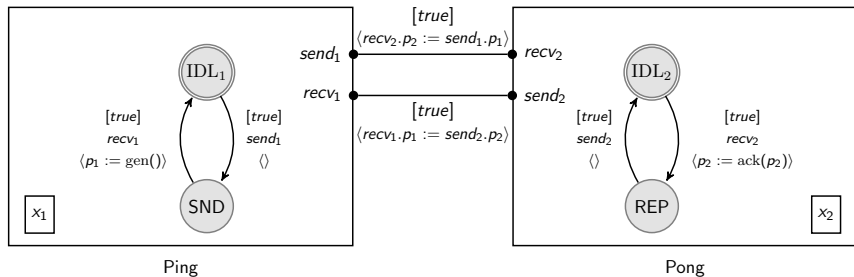
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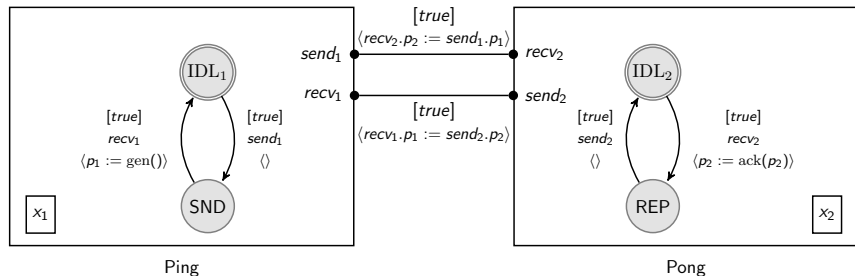


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- $map(E_0, B_0) = \langle \langle IDL_1, \langle 1 \rangle \rangle, send_1, \langle SND, \langle 1 \rangle \rangle \rangle$
- $map(E_0, B_1) = \langle \langle IDL_2, \langle 0 \rangle \rangle, recv_2, \langle REP, \langle 2 \rangle \rangle \rangle$

Local Pointcuts

Location

$e = \langle \langle l, v \rangle, \tau, \langle l', v' \rangle \rangle \models lpc$ iff match lpc with:

$$| \text{atLocation}(\ell) \quad \rightarrow (l = \ell)$$

Local Pointcuts

Variables

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atLocation(ℓ)	$\rightarrow (l = \ell)$
readVarGuard(x)	$\rightarrow (\exists t \in B_k.trans : t.src = l \wedge x \in readguard(t))$
readVarFunc(x)	$\rightarrow (x \in readvar(\tau.func))$
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Ports

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portEnabled(p)	$\rightarrow (\exists q' : \langle \langle l, v \rangle, p, q' \rangle \in \rightarrow_{B_k})$

Local Pointcuts

Ports

$e = \langle\langle l, v \rangle, \tau, \langle l', v' \rangle\rangle \models lpc$ iff $match\ lpc$ with:

atLocation(ℓ)	$\rightarrow (l = \ell)$
readVarGuard(x)	$\rightarrow (\exists t \in B_k.trans : t.src = l \wedge x \in readguard(t))$
readVarFunc(x)	$\rightarrow (x \in readvar(\tau.func))$
write(x)	$\rightarrow (x \in writevar(\tau.func))$
portEnabled(p)	$\rightarrow (\exists q' : \langle\langle l, v \rangle, p, q' \rangle \in \rightarrow_{B_k})$
portExecute(p)	$\rightarrow (\tau.port = p)$

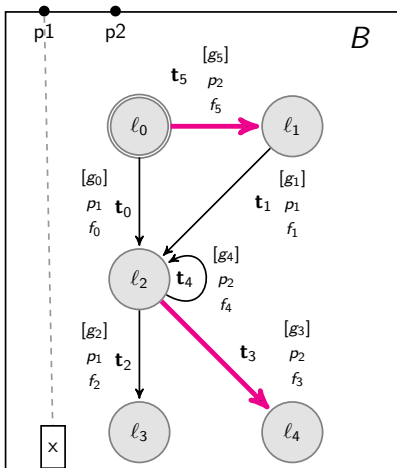
Local Pointcuts

Combination

$e = \langle \langle l, v \rangle, \tau, \langle l', v' \rangle \rangle \models lpc$ iff match lpc with:

atLocation(ℓ)	$\rightarrow (l = \ell)$
readVarGuard(x)	$\rightarrow (\exists t \in B_k.trans : t.src = l \wedge x \in readguard(t))$
readVarFunc(x)	$\rightarrow (x \in readvar(\tau.func))$
write(x)	$\rightarrow (x \in writevar(\tau.func))$
portEnabled(p)	$\rightarrow (\exists q' : \langle \langle l, v \rangle, p, q' \rangle \in \rightarrow_{B_k})$
portExecute(p)	$\rightarrow (\tau.port = p)$
ϕ and ϕ'	$\rightarrow e \models \phi \wedge e \models \phi'$

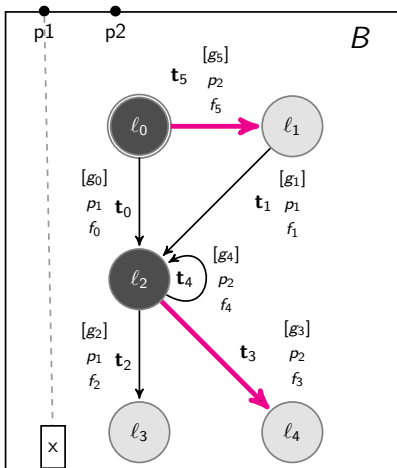
Syntactic Representation



$$M = \{t_3, t_5\}$$

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2		l_4

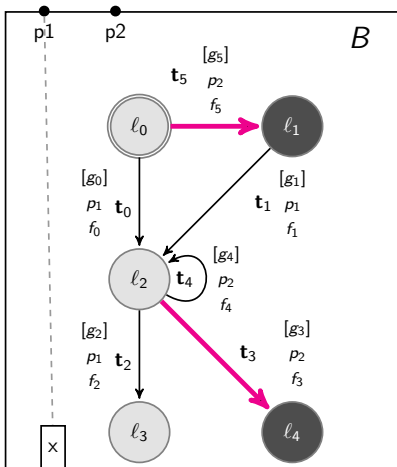
Syntactic Representation



origin(M)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2		l_4

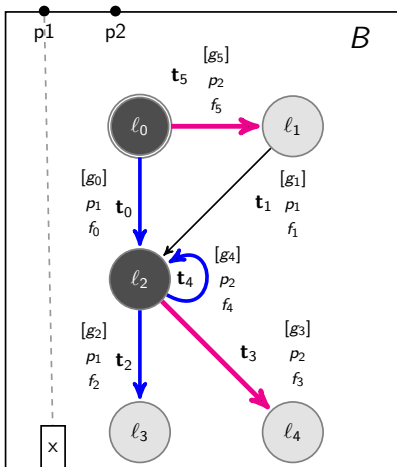
Syntactic Representation



$\text{dest}(M)$

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2	l_4	

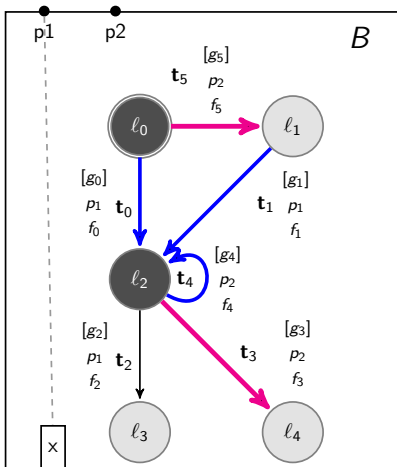
Syntactic Representation



siblings(M)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2	l_4	

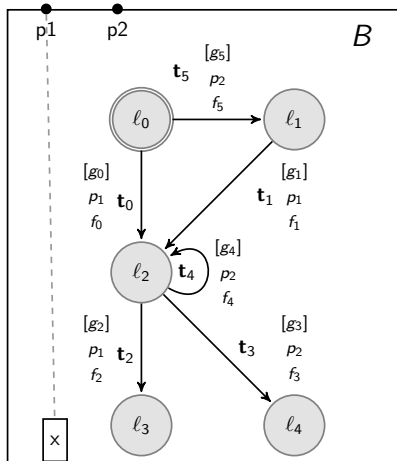
Syntactic Representation



previous(M)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2		l_4

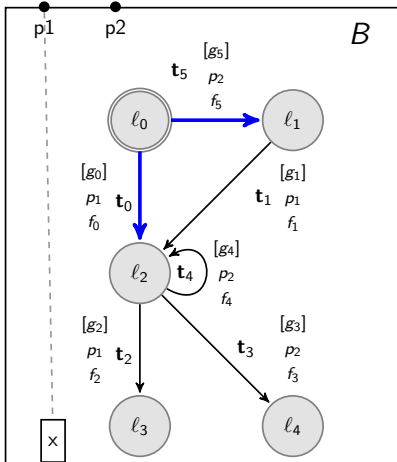
Matching Pointcuts



$$g_3 = x > 3$$

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2	l_4	

Matching Pointcuts



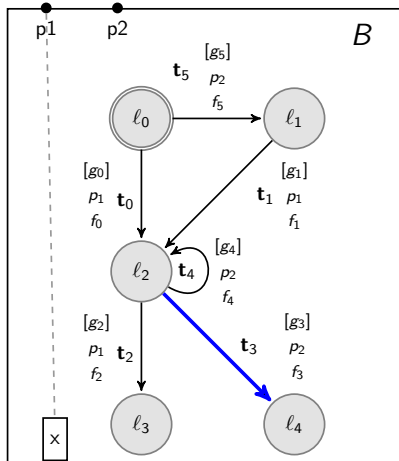
$$g_3 = x > 3$$

atLocation(l_0)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2

l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2		l_4

Matching Pointcuts

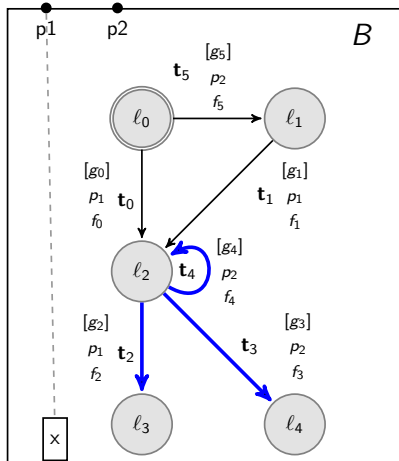


$$g_3 = x > 3$$

readVarGuard(x)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
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Matching Pointcuts

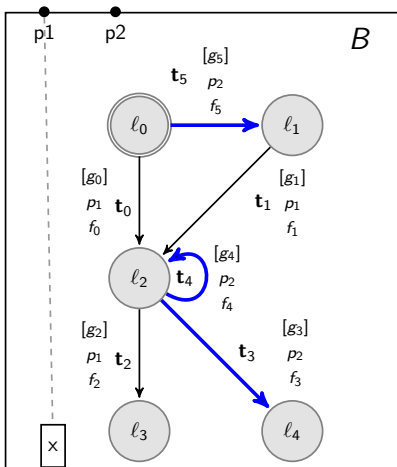


$$g_3 = x > 3$$

readVarGuard(x) [Siblings]

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2	l_4	

Matching Pointcuts

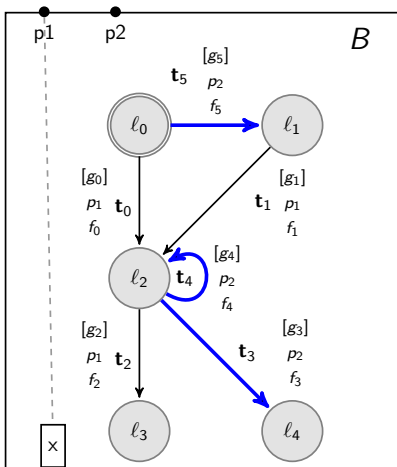


$$g_3 = x > 3$$

portExecute(p_2)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
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		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
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Matching Pointcuts

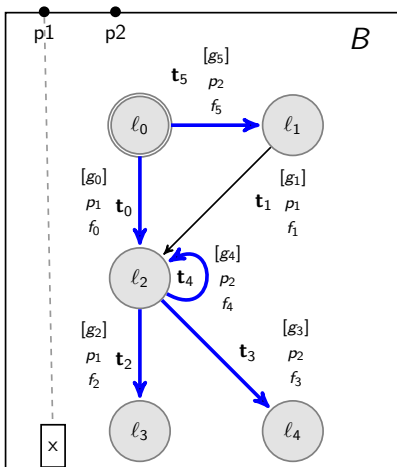


$$g_3 = x > 3$$

portEnabled(p_2)

l_0		l_2	
$t_0 : \langle g_0, p_1, f_0 \rangle$	l_2	$t_2 : \langle g_2, p_1, f_2 \rangle$	l_3
$t_5 : \langle g_5, p_2, f_5 \rangle$	l_1	$t_3 : \langle g_3, p_2, f_3 \rangle$	l_4
		$t_4 : \langle g_4, p_2, f_4 \rangle$	l_2
l_1		l_3	
$t_1 : \langle g_1, p_1, f_1 \rangle$	l_2	l_4	

Matching Pointcuts



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portEnabled(p_2)[Siblings]

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Local Advice

- ① A function f_b to execute **before** the update function.
- ② A function f_a to execute **after** the update function.

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- ② A function f_a to execute **after** the update function.
- ③ A set of "reset location" pairs $\langle l, g \rangle$: after joinpoint move to l if g holds.

Local Weaving

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- Dynamic behavior: **portEnabled**, **reset location**
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 - **Pre-evaluate** guards in an earlier **temporary** location
 - Simulate **if/else** construct by duplicating transitions

Composition (Overview)

- Conditions for interference
 - Multiple concerns can **overlap** one region
 - Not all concerns are **independent**
 - Possibility to have **non-determinism** or **unwanted side-effects**

Composition (Overview)

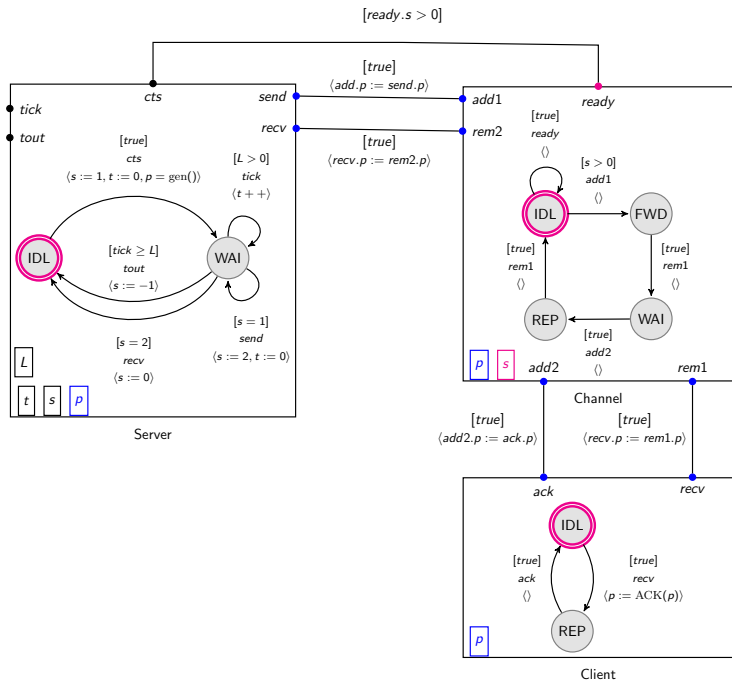
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Composition (Overview)

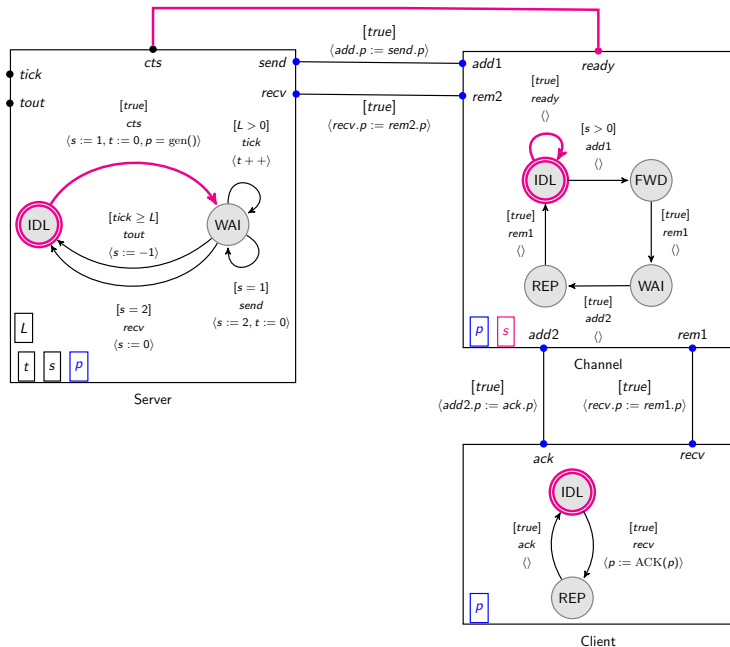
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 - Weaving **procedures**: match/weave strategy

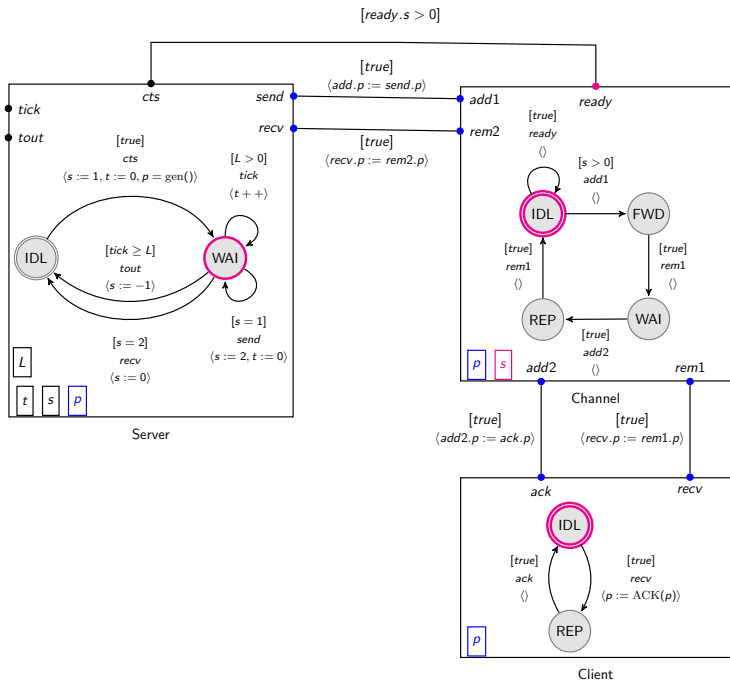
Using AOP-BIP Network Example ¹

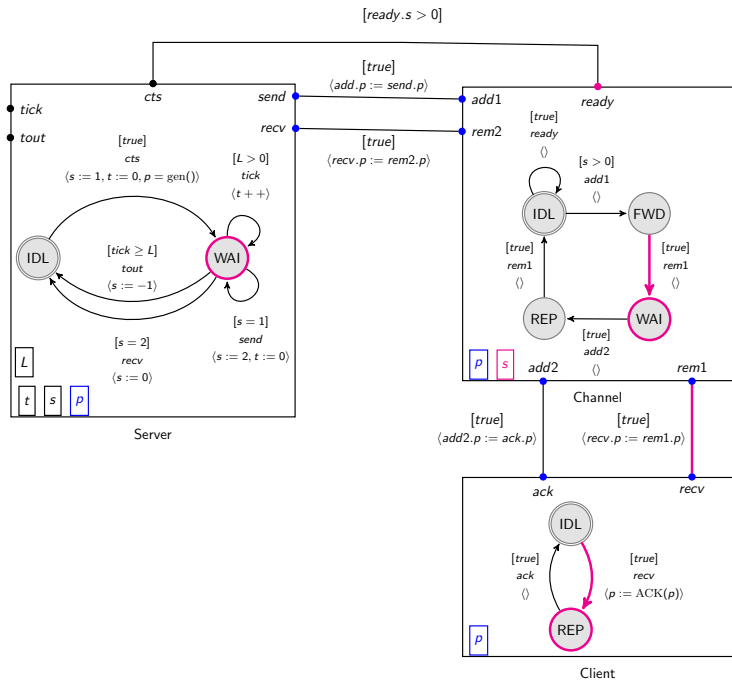
¹A modified version of the network in [Bonakdarpour et al., 2012]

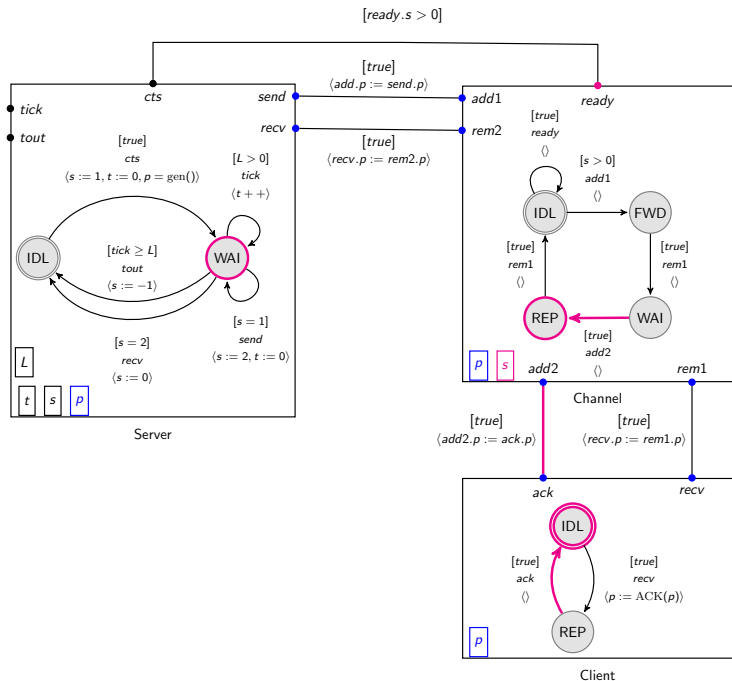


$[ready.s > 0]$

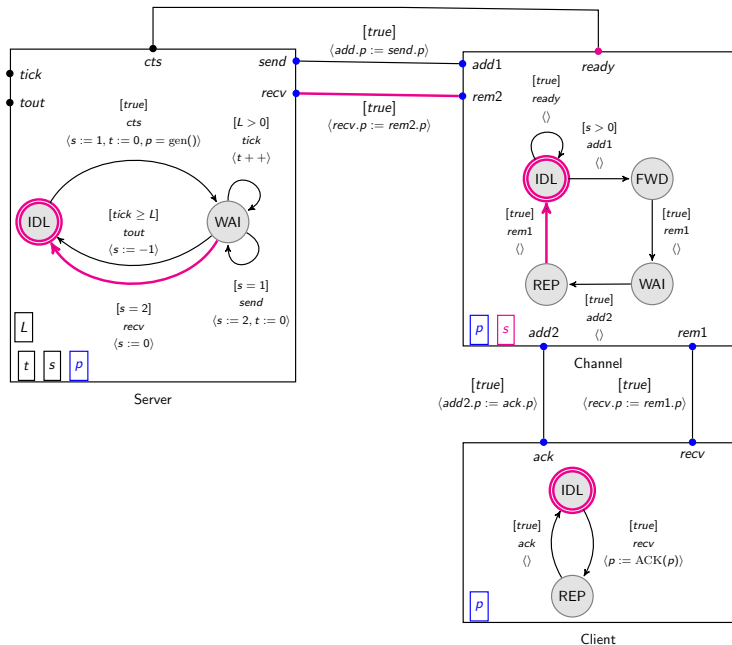


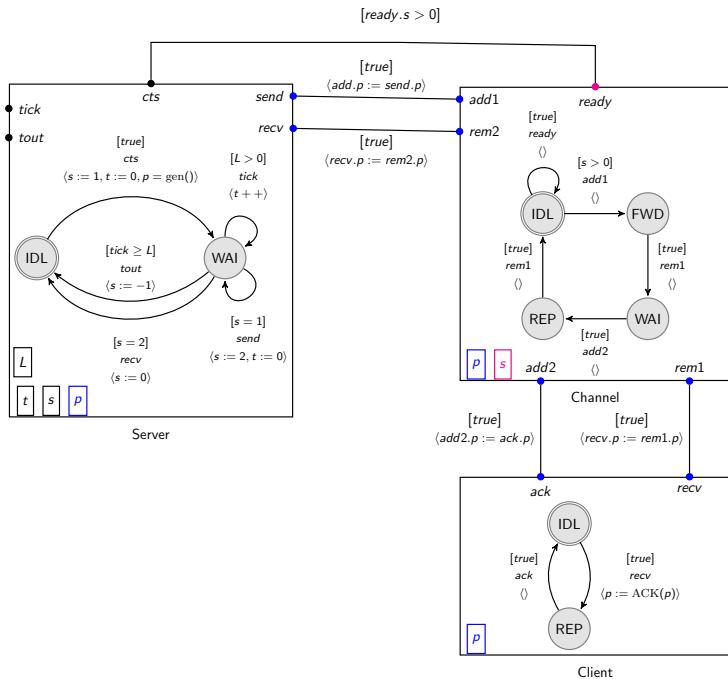






$[ready.s > 0]$





Authentication Concern

```
Aspect AddHash (server) {  
  portExecute(cts)  
  do {} {p = wrap(p); }  
}  
Aspect VerifyHash (channel) {  
  data int clear = 0  
  portExecute(add1)  
  do {} {clear = check(p); p = unwrap(p);}  
  {(IDL, clear == 0)}  
}  
Aspect Carol {  
  ports(a:server.send b:channel.add1)  
  readPortVars(a.r)  
  do {} {b.r = pfake(a.r);}  
}
```


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  portExecute(cts)
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Aspect Carol {
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  readPortVars(a.r)
  do {} {b.r = pfake(a.r);}
}

```

```

[Server.cts ] Clear to Send
[Server.send ] -> 886|6 (Time: 0)
[Channel.add1] <- 386|6
[Channel.rem1] -> 386
[Client.recv ] <- ACK
[Client.ack ] -> ACK
[Channel.add2] <- ACK
[Channel.rem2] -> ACK
[Server.recv ] <- ACK (Time: 3)

[Server.cts ] Clear to Send
[Server.send ] -> 763|3 (Time: 0)
[Channel.add1] <- 736|3
[Server.tout ] Timeout

```

Concern Coverage

- Complexity to implement a crosscutting concern
- Scattering and Tangling

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#	Concern	Scattering		Tangling		
		Transitions	Interactions	OT	OI	OC
1	Logging	10	0	5	0	2, 3
2	Authentication	2	1	2	1	1, 3, 4
3	Congestion	5	0	4	0	1, 2
4	Fault Tolerance	0	3	0	1	2
Network		12	5			

OT: Overlapping Transitions | OI: Overlapping Interactions | OC: Overlapping Concerns

Applications to RV

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 - ③ Use inter-type to store monitor state

Applications to RV

- Runtime Verification is a **crosscutting concern** → use AOP-BIP for RV
 - ① Use pointcuts to describe joinpoints that are of interest (generate events)
 - ② Use advice functions to process events and also output trace (for offline)
 - ③ Use inter-type to store monitor state
- Considerations:
 - Simpler to describe transformations
 - Not as expressive as RV-BIP
(improves with extending pointcuts, advices and composition)

RV Example

- Data Robot: modules consisting of services
- Examples of existing tools RV – BIP [Falcone et al., 2015]
- Simplified simulation:
 - ① `clock` : components providing the global clock (`getTime`)
 - ② `poster`: interface to exchange data with other services
 - ③ `reader`: reads data of a poster (`read`)
 - ④ `writer`: writes data to a poster (`writenv` → `finishWrite`)
- Data exchanged is: `time` and `taskid`

RV Example - Monitors

Aspect MonMutex (poster) {

data int c = 0;

portExecute(writev)

do {checkConcurrent(c); c++;} {}

portExecute(finishWrite)

do {}{c--;}
}

Aspect MonFresh {

ports(r:reader.read p:poster.read c:clck.getTime)

do { checkFresh(c.x, p.x); } {}
}

Aspect MonOrder {

data int lastTask = 0

ports(p:poster.writev) **writePortVars**(p.x)

do {} { checkOrder(p.x, lastTask); lastTask = p.x; }
}

```
void checkConcurrent(int c) {
    if(c > 0)
        //Print violation
}
void checkFresh(int clock, int poster) {
    if(clock - poster > 2)
        //Print violation
}
void checkOrder(int task, int lastTask) {
    if (task != lastTask + 1)
        //Print violation
}
```


Conclusion

Summary

- Proposed a framework for **crosscutting concerns** in the BIP framework
- Focused on concerns at the level of the **coordination** between components
- Briefly overviewed local aspects and aspect composition
- Presented **AOP-BIP** and used it on a network example
(More details in the technical report and ujf-aub.bitbucket.org/aop-bip)
- Showed how it can be used for runtime verification of CBSs

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Future Work

- ① Expand the **expressiveness** of both pointcuts and advices
- ② Study in more detail aspect composition (strategies, designs)
- ③ Implement Model-to-Model transformation using **Domain Specific Languages** (DSLs) inspired from ATL and compare **expressiveness**.

Related Work

- AOP for CBS (not formal)
 - ① [Pessemier et al., 2008] Defining extra *advice* interfaces and using separate components for aspects.
 - ② [Duclos et al., 2002] Applying AOP to CBS by defining two languages
 - ③ [Lieberherr et al., 2003] Investigating aspects in **modules** (Java Packages)
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- Formal Approaches (not as simple/expressive)
 - ① [Katz, 2006, Djoko et al., 2012] Categorizing aspects and studying which properties are preserved for which classes of aspects
 - ② [Altisen et al., 2006] AOP for **reactive systems** presented as **Mealy automata**
 - ③ [Dihego and Sampaio, 2015] AOP for BRIC component model presented as Communicating Sequential Processes (**CSP**)

Language

```

aspect      : pointcuts 'do' advice;
pointcuts  : (pointcut)+ ;
pointcut   : pctype '(' IDENTIFIER ')';

pctype     : 'atLocation'
           | 'readVarGuard'
           | 'readVarFunc'
           | 'write'
           | 'portEnabled'
           | 'portExecute'
           ;

advice     : (before) (after) (resetlocs)? ;
before    : '{' actions '}';
after     : '{' actions '}';
resetlocs : '{' (rlocpair (',' rlocpair)*)? };
rlocpair  : '(' IDENTIFIER ',' expression );

gaspect   : gpoint 'do' before after
           ;
gpoint    : 'ports' '(' (portspec)+ ')' (gread)? (gwrite)?
           | 'ports' '(' (portspec)+ ')' (gwrite)? (gread)?
           ;

gwrite    : 'writePortVars' '(' port_var+ ')';
gread     : 'readPortVars' '(' port_var+ ')';

portspec  : IDENTIFIER ':' port_name ;
port_name : IDENTIFIER '.' IDENTIFIER;
port_var  : IDENTIFIER '.' IDENTIFIER;

```

Language

```

file      : (CODE)? (container)+ ;





container : 'Aspect' IDENTIFIER '{' intertype (gaspect)+ '}'
          | 'Aspect' IDENTIFIER '(' IDENTIFIER ')'
            '{' intertype (aspect)+ '}'
          ;




CODE      : '#{ .*? }#';


intertype : (intertypedef)*
          ;

intertypedef
  : 'data' IDENTIFIER IDENTIFIER
  | 'data' IDENTIFIER IDENTIFIER '=' literal_expression
  ;

```

-  Altisen, K., Maraninchi, F., and Stauch, D. (2006).
Aspect-oriented programming for reactive systems: Larissa, a proposal in the synchronous framework.
Sci. Comput. Program., 63(3):297–320.
-  Bonakdarpour, B., Bozga, M., and Göbller, G. (2012).
A theory of fault recovery for component-based models.
In Richa, A. W. and Scheideler, C., editors, *Stabilization, Safety, and Security of Distributed Systems - 14th Int. Symposium, SSS 2012, Toronto, Canada, October 1-4, 2012. Proc.*, volume 7596 of *LNCS*, pages 314–328. Springer.
-  Czarnecki, K., Eisenecker, U. W., and Steyaert, P. (1997).
Beyond objects: Generative programming.
In *The 23rd Int. Conf. On Software Engineering*, pages 5–14.
-  David, P. and Ledoux, T. (2006).
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